

The Power of Choice

EPSON

The Best Just Got Better

EPSON G-Series SCARA Robots

- High Speed Improvements of up to 20% vs. our already fast E2 Series
- Heavy Payloads Increased payload capacities up to 20%
- Wide Variety 200+ different G-Series models available from 175 1,000mm
- Large Work Envelopes Expanded motion range up to 23%
- Extended Z Axis Available for applications (like packaging) requiring longer strokes
- **High Precision** Repeatabilities down to 15 microns
- Washdown models IP65 and IP54 models available in most sizes and configurations
- Cleanroom Models ISO 3 Clean & ESD models available in all sizes and configurations
- Ease of Use Industry leading EPSON RC+ significantly reduces development time vs. competitive products
- Low Cost G-Series robots run on the low cost EPSON Micro PowerDrive RC180
- Fully Integrated Options Vision Guidance, .NET Connectivity, DeviceNet, EtherNet/IP, Profibus, Expansion I/O and more...

200+ G-Series Models

Look no further for your next SCARA robot as EPSON Robots give you more Power of Choice than ever before. With 200+ models available in sizes from 175 – 1,000mm in reach and payloads of up to 20kg, chances are that EPSON has the model and configuration you need for your next application.

EPSON G-Series robots feature Max-R, a new high rigidity arm design that achieves ultra-high speed, ultra-high precision and low vibration. This puts EPSON G-Series robots in the top of their class. With speeds and payload improvements of up to 20% vs. our already fast E2 Series SCARA models, **THE BEST JUST GOT BETTER!**

EPSON G-Series SCARA robots are ideally suited for the Medical, Automotive, Electronics, Consumer, Food, Lab Automation, Semiconductor, Plastics, Appliance, Aerospace industries and many more. They can be used for a wide variety of applications ranging from pace maker assembly to DNA testing or from chain saw to hard drive assembly. There are tens of thousands of different applications that our robots can handle. Let us help you with yours.

EPSON G-Series Configurations

	•							
	G1	G3	G6	G10	G20			
Payload (Max./Rated)	1/0.5kg	3/1kg	6/3kg	10/5kg	20/10kg			
Reach (Axis 1 + Axis 2) 175mm 225mm 250mm 300mm 350mm 450mm 550mm 650mm 850mm 1,000mm	• • - - - - -	- - • • - - -	- - - - - • •	- - - - - - -	- - - - - - -			
Z-axis length*1 100mm 150mm 180mm 330mm 420mm	• - - -	- • - -	- - • •	- - • -	- - • -			
Configurations Standard Wall/Ceiling mount Cleanroom/ESD IP54/IP65	• - • -	•	•	•	•			

*1 The usable Z-axis length is shortened by 20-30mm for cleanroom and IP54 / IP65 machines.



Mounting Configurations



All EPSON G-Series robots are available in wall, ceiling or table top mounting configurations to help maximize available workspace. While table top models are the most commonly used, EPSON Robot users love the ceiling and wall mount configurations to run conveyors underneath. With such a wide range of product and mounting configurations, chances are that EPSON has the right robot for your next application.

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Protected Models - IP54 and IP65

EPSON G-Series Protected Models are available for those applications that require an extra level of dust or water resistance. Our G-Series washdown and dustproof robots are perfect for applications such as food handling, industrial applications, etc. A large selection of G-Series models are available in either IP54 or IP65 configurations.

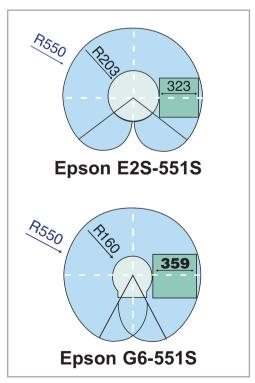
IP54 (Dust) - Dust shall not ingress in a quantity to interfere with satisfactory operation of the robot

IP54 (Water) - Water splashing against the enclosure from any direction shall have no harmful effect

IP65 (Dust) - No ingress of dust

IP65 (Water) - Water projected by a nozzle against enclosure from any direction shall have no harmful effects

G6 Design Increases Working Range



Comparison of the working ranges

While it may seem impossible, our G6 550mm robots can handle many applications with large working range requirements that other robots need 600mm of reach to handle. With up to a 23% larger working range vs. previous and competitive models, **EPSON G-Series robots lead the industry in footprint to workspace ratios**. Just look at the advantages of the G-Series:

- Smaller workcells help save valuable factory space
- Increased range of motion (G-Series reaches far behind itself)
- Larger working quadrangle allows use of larger pallets (see figure at left)

ISO 3 Clean & ESD

Cleanroom G-Series models include additional features such as special Z-Axis bellows, special covers, cover seals, etc. to reduce particulates emitted by the robot to enable use in cleanroom environments. EPSON ISO 3 Clean & ESD robots are widely used in the Hard Drive and Semiconductor industries due to their reliability, outstanding performance and ease of use while also maintaining high cleanroom and ESD compliance. Some of the additional key features for EPSON Cleanroom/ESD models are shown below:

- All EPSON G-Series models and sizes are available in ISO 3 Clean configurations
- All EPSON cleanroom robots are also ESD compliant.*1 This makes them ideal for ESD sensitive applications where electro-static discharge can create defective parts such as the hard drive industry.
- Internal vacuum lines are included to draw air from the base and arm cover interiors

^{*1} EPSON Robots was the first major assembly robot vendor to introduce ESD compliant robots which are now widely used in the hard drive and electronics industries.



G1 SCARA Robots

- Arm Lengths from 175 to 225mm
- Industry Leading Precision Assembly
- Best in Class Cycle Rates
- Maximum Work Envelope Usage
- Ultra Compact yet Extremely Powerful
- High Rigidity Arm = Ultra High Speed
- Robust Design for Excellent Durability
- ISO 3 Clean & ESD Compliant Models
- Fully Integrated Options including:
 Vision Guidance, .Net Connectivity, EtherNet/IP,
 DeviceNet, Profibus, Expansion I/O and more



Industry Leading Mini SCARA

EPSON G1 robots are the low cost, high performance leader for mini SCARA Robots. With best in class cycle rates and motion range, G1 robots are the most powerful and compact mini SCARAs available in the market today.

G1 Mini SCARAs provide everything you've come to expect from EPSON Robots except they are smaller. Our 225mm robot arms can handle many applications with large working range requirements that other robots need 250mm of reach to handle. G1 robots lead the industry in footprint to workspace ratios. Imagine now being able to use a 225mm arm for applications that used to require a much larger 250mm SCARA arm - What a great saving of valuable floor space.

High rigidity construction combined with superior controls enable G1 arms to achieve industry leading speed and precision. 3-axis models allow for superior performance for press fit screw tightening and linear dispensing applications.

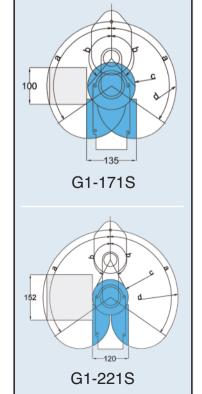
G1 robots are ideally suited for applications and industries which require high precision assembly of small components, demanding cycle times and compact production lines.



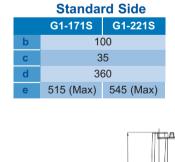
G1 Specifications

				•		-	
			4-a		3-a		
			G1-171	G1-221	G1-171	G1-221	
Arm Length (mm)		Horiz. (J1 + J2)	75 + 100 = 175	125 + 100 = 225	75 + 100 = 175	125 + 100 = 225	
Payload (kg)		Max. / Rated	1 /	0.5	1 / 0).5	
Repeatability	mm	J1 + J2	+/-0.005	+/-0.008	+/-0.005	+/-0.008	
		J3		+/-0	.010		
	deg	J4	+/-0	.01	-		
Cycle Time*1			0.29	0.30	0.29	0.30	
Max. Operating	mm/sec	J1 + J2	2,630	3,000	2,630	3,000	
Speed	11111/300	J3		1,2	00		
	deg/sec	J4	3,0	00		-	
Motor Wattage (W)			50 / 50 /	50 / 50	50 / 50 / 50		
Insertion Force				50N (5.1 kgf)			
U inertia	kg⋅m²	Max. / Rated	0.004 /	0.0003		-	
Axis Motion Range		J1 (deg)	+/-125		+/	125	
		J2 (deg)	+/-140*2 (+/-140)*3	+/-152*2 (+/-149)*3	+/-135*2 (+/-123)*3 +/-135*2 (+/-132)3		
		J3 (mm)	100*2 (80)*3				
		J4 (deg)	+/-360				
User Lines		Electric	24 lines (15pin, 9pin)				
		Air	Ø4 x 1, Ø6 x 2				
Z Axis Diameter (m	m)		08				
Mounting Hole Foo	tprint (mm)	125 x 88 (4-M6)				
Weight (kg)			8				
Environmental		Temperature		5 - 40) deg C		
		Humidity		10 - 80% (non	condensing)		
Optional Arm Configurations Mounting Type		Mounting Type	Tabletop				
Clean & ESD			ISO 3 Clean & ESD				
Robot Cables (Met	ers)		3M (standard) / 5M (optional) / 10M (optional)				
Available Controlle	rs		Micro PowerDrive RC180				
				PC Based Con	troller RC620+		

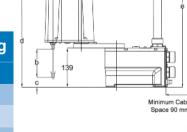
G1 Dimensional Drawings for Work Envelope and Installation



Standard Top						
	G1-171S	G1-221S				
а	75	125				
108	100 a	208	10			



Installation Dimension	Table-Top mounting		
Model	G1-171S	G1-221S	
a-Motion range of Joint #1 (deg)	+/-1	25	
b-Motion range of Joint #2 (deg)	+/-140	+/-152	
c-Inner working radius (mm)	64	60	
d-Reach (mm)	175	225	
Largest working quadrangle (mm²)	100	152	



Maximum motion range varies for cleanroom models. Contact Epson for detailed information

G3 SCARA Robots

- Arm Lengths from 250 to 350mm
- Leader in its Class for both Cycle Time and Precision
- Best in Class Motion Range
- Small yet Extremely Powerful
- Robust Design for Excellent Durability
- ISO 3 Clean & ESD Compliant Models
- Fully Integrated Options including: Vision Guidance, .Net Connectivity, EtherNet/IP, DeviceNet, Profibus, Expansion I/O and more



Compact, Ultra Powerful and Low Cost

EPSON G3 robots lead the industry with best in class cycle time, precision and motion range. Simply put, they are the low cost, high performance leader for small SCARA Robots. With over 30 models available in sizes from 250 - 350mm, G3 robots are able to meet the demanding space requirements of factories with limited workspace areas.

Unique to the G3 is our new curved arm option to maximize work envelope usage. Our 350mm curved arm model is able to match the motion range of larger 400mm class SCARA robots, thus saving our customers valuable floor space.

A small footprint and high performance capabilities make EPSON G3 robots perfect for applications and industries requiring demanding cycle times, high precision and high reliability such as: hard disk assembly, lab automation, electronics, medical device assembly, photonics, semiconductor, telecommunications and many others.



G3 Specifications

			- G3-251	G3-301	G3-351	
Arm Length (mm)		Horiz. (J1 + J2)	120 + 130 = 250	170 + 130 = 300	220 + 130 = 350	
Payload (kg)		Max. / Rated	120 + 130 = 230	3 / 1	220 + 130 = 330	
Repeatability		J1 + J2	+/-0.008		0.010	
mm		J3	+/-0.000	+/-0.010	0.010	
	deg	J4		+/-0.005		
Cycle Time*1	ueg	<u> </u>	0.36	0.37	0.37	
Max. Operating		J1 + J2	3,550	3,950	4,350	
Speed	mm/sec	J3	3,330	1,100	4,550	
Opecu	deg/sec			3,000		
Motor Wattage (W		<u> </u>		200 / 150 / 150 / 150		
Insertion Force	/			150N (15.3 kgf)		
U inertia	kg·m²	Max. / Rated		0.05 / 0.005		
O mortiu	- Kg III	Table Top Mount:				
		Straight Arm		+/-140		
		Curved Right	_	-125 to +150	-110 to +165	
	J1	Curved Left	_	-150 to +125	-165 to +110	
	(deg)	Multimount (Ceiling Wall):			100.00	
	(, , , , ,	Straight Arm	_	+/-115	+/-120	
		Curved Right	_	_	-105 to +130	
Axis Motion Range		Curved Left	_	_	-130 to +105	
		Table Top Mount:				
, and the second se		Straight Arm	+/-141*2 (+/-137)*3	+/-142*2 (+/-141)*3	+/-142*2 (+/-142)*3	
		Curved Right	_	-135 to +150*2 (-135 to +145)*3	-120 to +165*2 (-120 to +160)*3	
	J2	Curved Left	_	-150 to +135*2 (-145 to +135)*3	-165 to +120*2 (-160 to +120)*3	
	(deg)	Multimount (Ceiling Wall):				
		Straight Arm	_	+/-135	+/-142	
		Curved Right	_	_	-120 to +160*2 (-120 to +150)*3	
		Curved Left	_	-	-160 to +120*2 (-150 to +120)*3	
	J3 (mm)	Standard		+150*2 (120)*3		
	J4 (deg)	All	+/-360			
User Lines		Electric		15 lines (15pin)		
		Air		Ø4 x 1, Ø6 x 2		
Z Axis Diameter (r	nm)			Ø16		
Mounting Hole Fo	otprint (mn	n)		120 x 120 (4-M8)		
Weight (kg)		Table Top Mount		14		
Multimount (Ceiling/Wall):		N/A		14		
Environmental		Temperature		5 - 40 deg C		
Humidity				10 - 80% (non condensing)		
Optional Arm Mounting Type		N/A Multimount				
Configurations Clean & ESD		ISO 3 Clean & ESD				
Robot Cables (Me			3M (standard) / 5M (optional) / 10M (optional)			
Available Controll	ers		Micro PowerDrive RC180			
				PC Based Controller RC620+		
*1: Cycle time based on 1	kg payload	*2: Standard configuration *3: C	Clean & ESD configuration			

^{*1:} Cycle time based on 1kg payload *2: Standard configuration *3: Clean & ESD configuration







G3 Work Envelope Dimensions

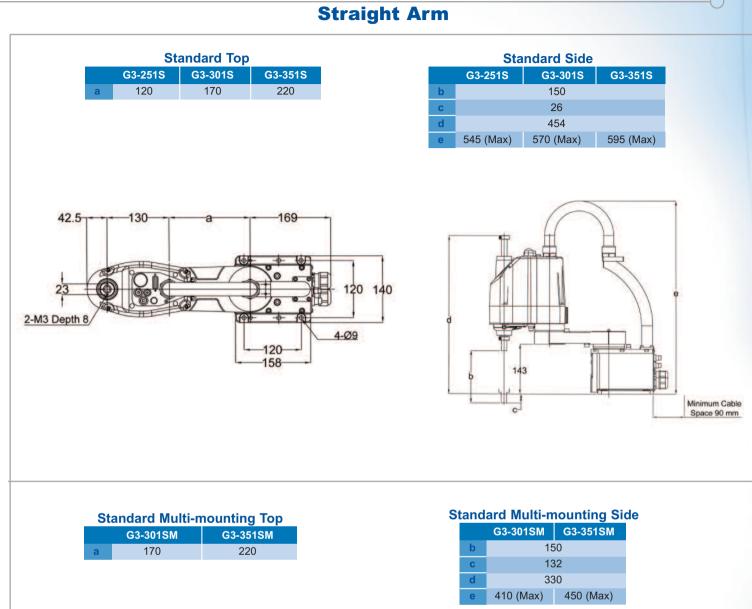
Straight Arm

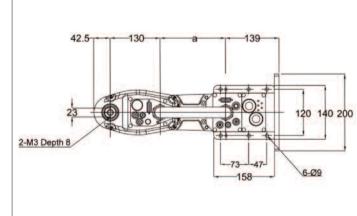
Table Top mounting **Multi-mounting** G3-251S 176 G3-301S G3-301SM G3-351S G3-351SM

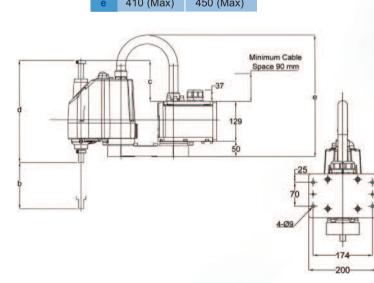
Installation Dimension	Та	ble-Top mour	Multi-mounting		
Model	G3-251S	G3-301S	G3-351S	G3-301SM	G3-351SM
a-Motion range of Joint #1 (deg)		140+/-		115+/-	120+/-
b-Motion range of Joint #2 (deg)	141+/-	142+/-		135+/-	142+/-
c-Inner working radius (mm)	84	105	142	121	142
d-Reach (mm)	250	300	350	300	350
Largest working quadrangle (mm²)	151	181	194	145	191

Maximum motion range varies for cleanroom, protected models. Contact Epson for detailed information.

G3 Dimensional Drawings for Installation

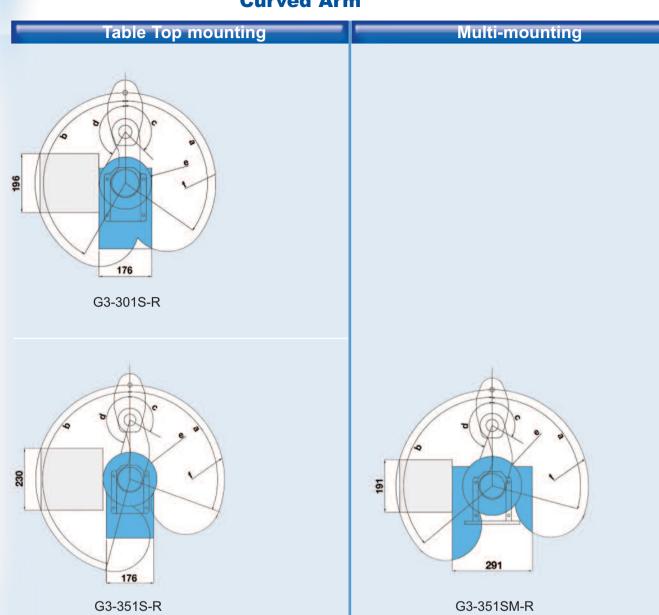






G3 Work Envelope Dimensions

Curved Arm

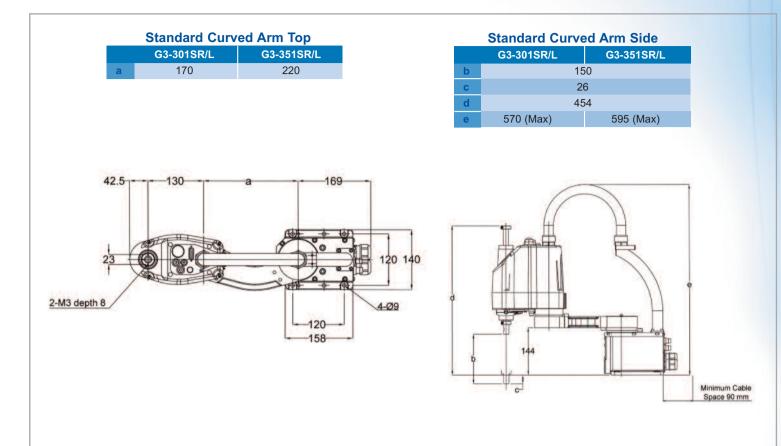


Installation Dimension		Table-Top	Multi-mounting			
Model	G3-301SR	G3-301SL	G3-351SR	G3-351SL	G3-351SMR	G3-351SML
a-Motion range of Joint #1 (deg)	125	150	110	165	105	130
b-Motion range of Joint #1 (deg)	150 125		165	110	130	105
c- Motion range of Joint #2 (deg)	135	150	120	165	120	160
d-Motion range of Joint #2 (deg)	150 135		165	120	160	120
e-Inner working radius (mm)	8	37	10	00	108	
f- Reach (mm)	30	00	350			
Largest working quadrangle (mm²)	19	96	230		191	

Maximum motion range varies for cleanroom, protected models. Contact Epson for detailed information.

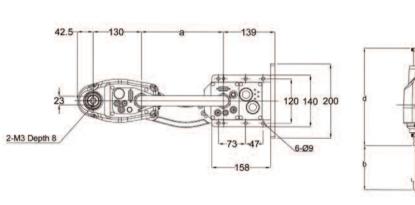
G3 Dimensional Drawings for Installation

Curved Arm



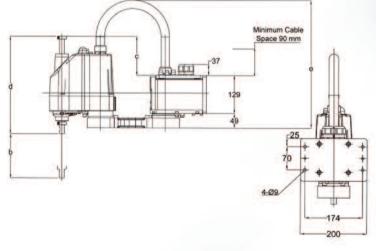


220



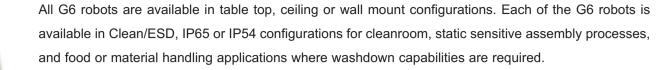
Standard Curved Arm Multi-mounting Side

G3-351SMR/L							
b	150						
С	132						
d	330						
е	450 (Max)						



G6 SCARA Robots

- Arm lengths from 450 to 650mm
- High Rigidity Arm = Ultra High Speed
- Best in Class Motion Range
- Increased Payloads by 20%
- Tabletop, Ceiling and Wall Mount models
- IP54 and IP65 Washdown / Dustproof models
- ISO 3 Clean & ESD compliant models
- Fully integrated Options including: Vision Guidance, .Net Connectivity, EtherNet/IP, DeviceNet, Profibus, **Expansion I/O and more**
- Extended Z-Axis option for applications requiring longer strokes



With best in class working range, EPSON G6 robots are the compact footprint champion. But don't forget that EPSON G6 robots have ultra fast cycles, high repeatabilities and of course our famous EPSON reliability that is 2nd to none. In addition, our high performance controllers and EPSON RC+ development environment add the power, high servo performance and industry leading ease of use that make EPSON G6 SCARA robots the best choice for your next automation project.

G6 Specifications

ou opecifications							
		G6-45x	G6-55x	G6-65x			
Arm Length (mm)	Horiz. (J1 + J2)	200 + 250 = 450	300 + 250 = 550	400 + 250 = 650			
Payload (kg)	Max. / Rated		6/3				
Repeatability	J1 + J2		+/-0.015 mm				
	J3		+/-0.010 mm				
	J4		+/-0.005 deg				
Cycle Time [™]		0.33	0.36	0.38			
Max. Operating Speed	J1 + J2	6,440 mm/sec	7,170 mm/sec	7,900 mm/sec			
	J3 (180 / 330)	1,	100 / 2,350 mm/se	C			
	J4		2400 deg/sec				
Motor Wattage (W)		400 / 400 / 200 / 100					
Insertion Force		150N (15.3 kgf)					
U inertia	Max. / Rated		0.12 / 0.01 kg·m2				
User Lines	Electric	24 lines (15pin, 9pin)					
	Air		Ø6 x 2, Ø4 x 2				
Z Axis Diameter (mm)		Ø20					
Mounting Hole Footprint (mm)		150 x 150 (4-M8)					
Weight (kg)	Floor Mount	2		28			
	Ceiling Mount	2	7	28			
	Wall Mount	29		29.5			
Environmental	Temperature		5 - 40 deg C				
	Humidity	10 -	80% (non condens	sing)			
Optional Arm Configurations	Mounting Type		abletop, Ceiling, Wa				
	Clean & ESD IP Rating	ISO 3 Clean & ESD					
	IP54, IP65						
Available Controllers			ro PowerDrive RC				
		PC Based Controller RC620+					
*1: Cycle time based on 1kg payload							

Compact, High Speed and Powerful

EPSON G6 robots are part of our new G-Series line-up of next generation SCARA Robots. They are perfect for applications requiring high speed and high precision such as mechanical and electrical

> assembly, pick and place, kitting, dispensing and many others. Unique to the G6 is our new Max-E design which provides the maximum work envelope possible with an extremely compact footprint. Imagine doing jobs with a 550mm arm that previously required 600mm of reach. It's now possible with the EPSON G6 with Max-E.

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Extended Z-Axis

G6 robots come with either 180mm or 330mm Z axis stroke lengths (150mm or 300mm for Cleanroom/ESD and IP54/IP65 washdown models).

180mm Z axis-

330mm Z axis

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The Power of Choice

G6-65*S

G6 Work Envelope Dimensions

Table Top mounting Ceiling mounting Wall mounting G6-45*SW G6-45*S G6-45*SR 230 G6-55*S G6-55*SW G6-55*SR

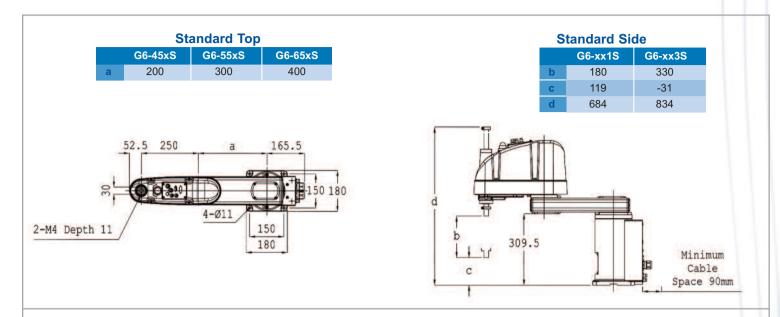
Installation Dimension	Table-Top mounting			Ceiling mounting			Wall mounting		
Model	G6-45**	G6-55**	G6-65**	G6-45**R	G6-55**R	G6-65**R	G6-45**W	G6-55**W	G6-65**W
a-Motion range of Joint #1 (deg)		+/-152		+/-120	+/-^	152	+/-105	+/-135	+/- 148
b -Motion range of Joint #2 (deg)	+/- 147.5			+/-130	+/-147.5		+/-130	+/-147.5	
c-Inner working radius (mm)	134.8	161.2	232	195.5	161.2	232	195.5	161.2	232
d-Reach (mm)	450	550	650	450	550	650	450	550	650
Largest working quadrangle (mm²)	290.6	359	388	238	359	388	238	349.2	388

G6-65*SR

G6-65*SW

Maximum motion range varies for cleanroom, protected models and Z position. Contact Epson for detailed information.

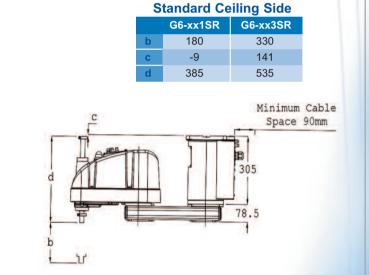
G6 Dimensional Drawings for Installation



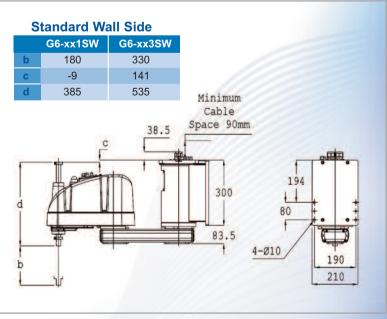
	Standard Ceiling Top							
	G6-45xSR	G6-55xSR	G6-65xSR					
а	200	300	400					
	F0 F 0F0		165 5					
	52.5 250	a	165.5					
	The second second	TE V	1					
			7 1					
8	O O 3: 10		1.					

180

Standard Wall Top



		G6-45xSW	G6-55xSW	G6-65
	а	200	300	400
			a	
		52.5 250	-1-	138
		A 10	9	1
	8	(d %; i		
			6	2
2-M4 Depth	11			
AT .				



G10 SCARA Robots

- Arm lengths from 650 to 850mm
- High Rigidity Arm = Ultra High Speed
- Increased Payload by 100% to 10 kg
- Reduced Residual Vibration for faster accel/decel rates
- Tabletop, Ceiling and Wall Mount models
- IP54 and IP65 Washdown/Dustproof models
- ISO 3 Clean & ESD compliant models
- Fully integrated Options including: Vision Guidance, .Net Connectivity, EtherNet/IP, DeviceNet, Profibus, Expansion I/O and more
- Extended Z-Axis available for applications requiring longer strokes

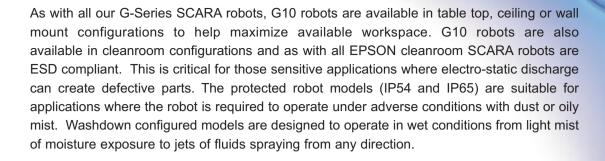
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High Rigidity = Ultra High Speed + Heavy Payload

> EPSON G10 robots are perfect for many different applications requiring high speed AND high payloads. G10 robots feature our Max-R design which gives a whole new meaning to high rigidity. G10 robots with Max-R are ultra high speed even with higher payloads. The rigid arm design

> > combined with powerful EPSON controls make G10 robots ideal for handling applications such as heavy parts assembly, machine tending, material handling, packaging, dispensing and more.... All which require high payloads and ultra high speed. G10 robots also maximize part throughput for even the most demanding cycle time requirements. This means more parts per hour and higher profits.

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G10 Specifications

Arm Length (mm) Payload (kg) Repeatability J1 + J2 J3 J4 Cycle Time" Max. Operating Speed J1 + J2 J3 (180 / 420) J4 Motor Wattage (W) Insertion Force U inertia Max. / Rated User Lines Electric	G10-65 x 250 + 400 = 650	G10-85 x 450 + 400 = 850				
Payload (kg) Repeatability J1 + J2 J3 J4 Cycle Time' Max. Operating Speed J1 + J2 J3 (180 / 420) J4 Motor Wattage (W) Insertion Force U inertia Max. / Rated	10 /					
Repeatability J1 + J2 J3 J4 Cycle Time" Max. Operating Speed J1 + J2 J3 (180 / 420) J4 Motor Wattage (W) Insertion Force U inertia Max. / Rated		. –				
J3 J4 Cycle Time*1 Max. Operating Speed J1 + J2 J3 (180 / 420) J4 Motor Wattage (W) Insertion Force U inertia Max. / Rated		5				
Cycle Time*1 Max. Operating Speed J1 + J2 J3 (180 / 420) J4 Motor Wattage (W) Insertion Force U inertia Max. / Rated	+/-0.025 mm					
Cycle Time ¹¹ Max. Operating Speed J1 + J2 J3 (180 / 420) J4 Motor Wattage (W) Insertion Force U inertia Max. / Rated	+/-0.010 mm					
Max. Operating Speed J1 + J2 J3 (180 / 420) J4 Motor Wattage (W) Insertion Force U inertia Max. / Rated	+/-0.005 deg					
Motor Wattage (W) Insertion Force U inertia J3 (180 / 420) J4 Max. / Rated	0.34	0.37				
Motor Wattage (W) Insertion Force U inertia J4 Max. / Rated	8,800 mm/sec	11,000 mm/sec				
Motor Wattage (W) Insertion Force U inertia Max. / Rated	1,100 / 2,350 mm/sec					
U inertia Max. / Rated	2400 de	eg/sec				
U inertia Max. / Rated	750 / 600 / 400 / 150					
	250N (25.5 kgf)					
User Lines Electric	0.25 / 0.02 kg•m2					
	24 lines (15pin, 9pin)					
Air	Ø6 x 2, Ø4 x 2					
Z Axis Diameter (mm)	02	5				
Mounting Hole Footprint (mm)	200 x 200 (4-M12)					
Weight (kg) Floor Mount	46	48				
Ceiling Mount	46	48				
Wall Mount	51	53				
Environmental Temperature	5 - 40 deg C					
Humidity	10 - 80% (non	condensing)				
Optional Arm Configurations Mounting Type	Tabletop, Ceiling, Wall					
Clean & ESD	ISO 3 Clean & ESD					
IP Rating	IP54, IP65					
Available Controllers	Micro PowerDrive RC180					
*1: Cycle time based on 2kg payload	Micro Powe	IDLING KC 180				

*1: Cycle time based on 2kg payload



Extended Z-Axis

G10 robots come with either 180mm or 420mm Z axis stroke lengths (150mm or 390mm for Cleanroom/ESD and IP54/IP65 washdown models).

420mm Z axis



The Power of Choice

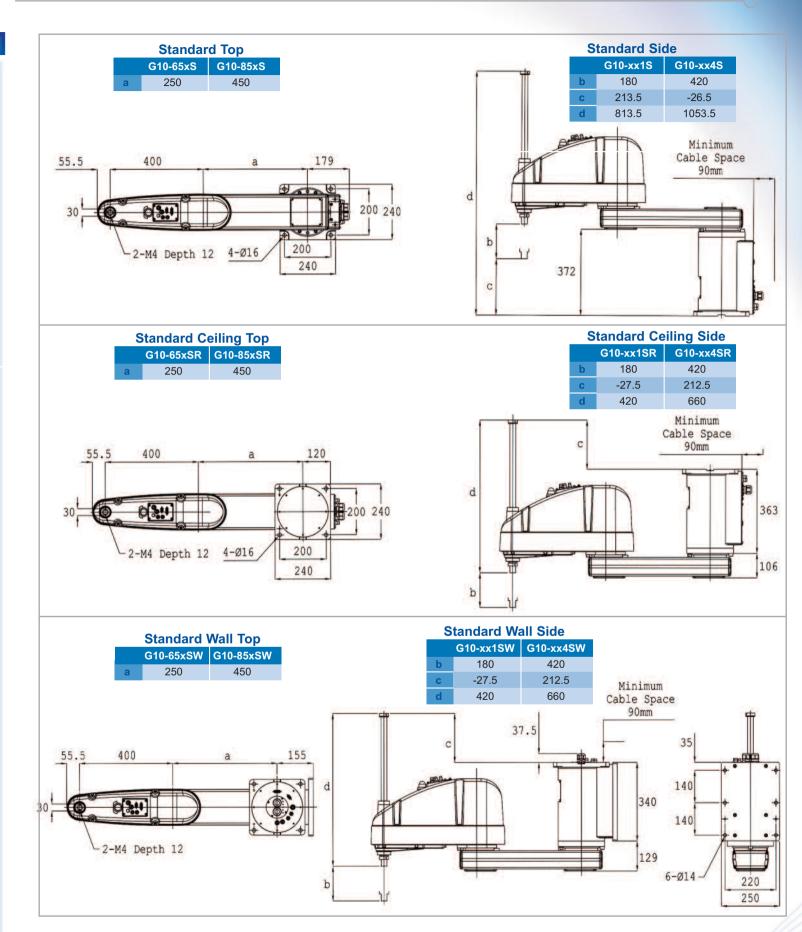
G10 Work Envelope Dimensions

Table Top mounting Ceiling mounting Wall mounting 400 400 270 G10-65*S G10-65*SR G10-65*SW 587.2 400 270 G10-85*S G10-85*SR G10-85*SW

Installation Dimension	Table-Top	mounting	Ceiling n	nounting	Wall mounting		
Model	G10-65**	G10-65** G10-85**		G10-85**R	G10-65**W	G10-85**W	
a - Motion range of Joint #1 (deg)	+/-1	52	+/-107	+/-152	+/-107		
b - Motion range of Joint #2 (deg)	+/-15	2.5	+/-130	+/-152.5	+/-130	+/-152.5	
c - Inner working radius (mm)	212.4 207.8		306.5	207.8	306.5	207.8	
d - Reach (mm)	650	850	650	850	650	850	
Largest working quadrangle (mm²)	405.1	587.2	323	587.2	323	587.2	

Maximum motion range varies for cleanroom, protected models and Z position. Contact Epson for detailed information

G10 Dimensional Drawings for Installation



G20 SCARA Robots

- Arm lengths from 850 to 1,000mm
- High Rigidity Arm = Ultra High Speed
- 20kg Payload
- Monocoque design provides for higher rigidity over longer lengths
- Tabletop, Ceiling and Wall Mount models
- IP54 and IP65 Washdown / Dustproof models
- ISO 3 Clean & ESD compliant models
- Fully integrated Options including:
 Vision Guidance, .Net Connectivity,
 EtherNet/IP, DeviceNet, Profibus, Expansion I/O and more
- Extended Z-Axis available for applications requiring longer strokes

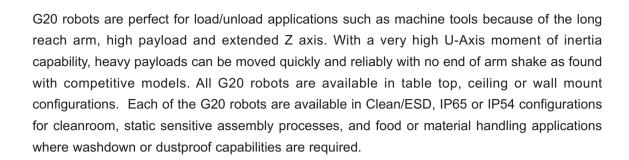
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Long Reach and Heavy Payload

G20 robots are ideal for applications involving transportation of heavy loads in large work areas, such as packaging, automotive, electrical, food, pharmaceutical, and medical as well as other industries - All which require heavy payloads, long reach and first class performance. G20 robots along with all G-Series robots, feature our Max-R high rigidity arm design which results in high speed performance AND heavy payloads along with higher duty cycles. G20 robots come with

either our Micro PowerDrive RC180 controller or our industry leading PC Based RC620+ controller. Both controllers feature powerful servo systems to maximize arm performance. With up to 20kg payload capacity and 850 or 1000mm arm reach, the G20 is the perfect robot for your larger jobs.

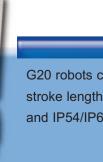
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G20 Specifications

		G20-85x	G20-A0x					
Arm Length (mm)	Horiz. (J1 + J2)	450 + 400 = 850	600 + 400 = 1000					
Payload (kg)	Max. / Rated	20 / 10						
Repeatability	J1 + J2	+/-0.025 mm						
	J3	+/-0.010 mm						
	J4	+/-0.005 deg						
Cycle Time ¹¹		0.37	0.42					
Max. Operating Speed	J1 + J2	11,000 mm/sec	11,500 mm/sec					
	J3 (180 / 420)	1,100 / 2,35	0 mm/sec					
	J4	1700 de	eg/sec					
Motor Wattage (W)		750 / 600 / 400 / 150						
Insertion Force		250N (25.5 kgf)						
U inertia	Max. / Rated	0.45 / 0.05 kg•m2						
User Lines	Electric	24 lines (15pin, 9pin)						
	Air	Ø6 x 2,						
Z Axis Diameter (mm)		Ø25						
Mounting Hole Footprint (n		200 x 200 (4-M12)						
Weight (kg)	Floor Mount	48	50					
	Ceiling Mount	48	50					
	Wall Mount	53	55					
Environmental	Temperature	5 - 40 c	•					
	Humidity		n condensing)					
Optional Arm Configuration		Tabletop, Ceiling, Wall						
	Clean & ESD	ISO 3 Clean & ESD						
	IP Rating	IP54, IP65						
Available Controllers		Micro PowerDrive RC180						
		PC Based Controller RC620+						
*1. Cycle time based on 2kg payload								

^{*1:} Cycle time based on 2kg payload



Extended Z-Axis

G20 robots come with either 180mm or 420mm Z axis stroke lengths (150mm or 390mm for Cleanroom/ESD and IP54/IP65 washdown models).

420mm Z axis →



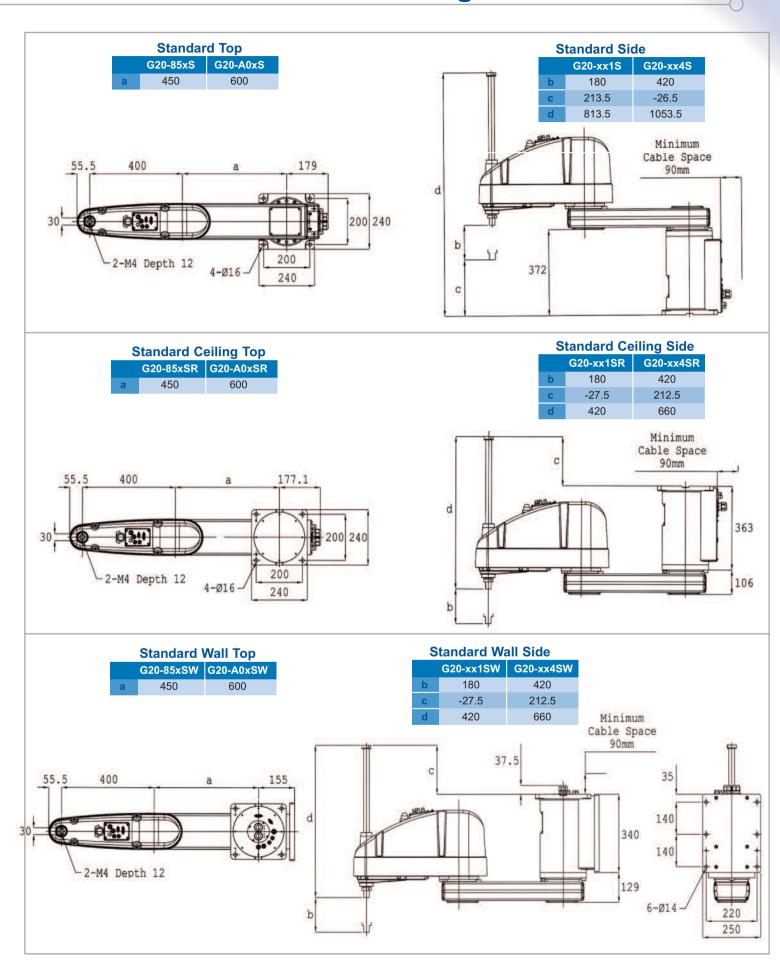
G20 Work Envelope Dimensions

Table Top mounting **Ceiling mounting** Wall mounting 270 G20-85*S G20-85*SR G20-85*SW 400 G20-A0*S G20-A0*SR G20-A0*SW

	Installation Dimension	Table-Top	mounting	Ceiling n	nounting	Wall mounting			
ľ	Model	G20-85**	55** G20-A0** G20-85**R G20-A0**R (20-85 **W G20-A0**W		
	a - Motion range of Joint #1 (deg)		+/	-152		+/-107			
	b - Motion range of Joint #2 (deg)	+/-152.5							
	c - Inner working radius (mm)	207.8	307	207.8	307	207.8	307		
	d - Reach (mm)	850	1000	850	1000	850	1000		
	Largest working quadrangle (mm²)	589	640.3	589	640.3	589	640.3		

Maximum motion range varies for cleanroom, protected models and Z position. Contact Epson for detailed information

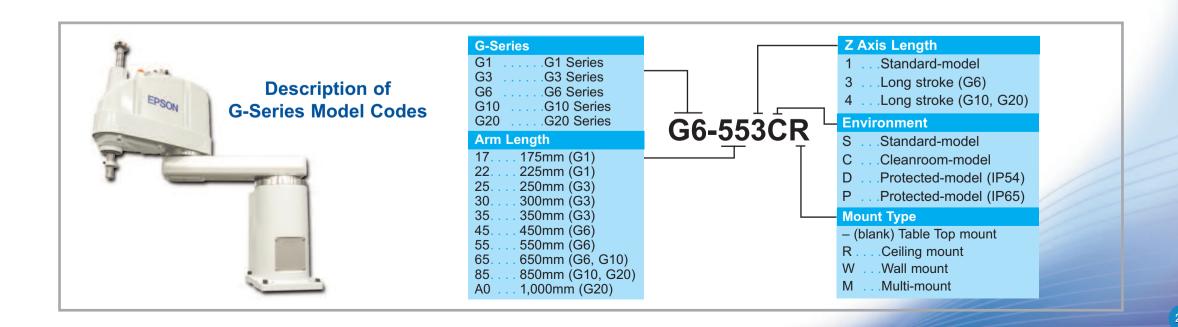
G20 Dimensional Drawings for Installation



EPSON G-Series Specifications

Ro	bot Mode	el	G1-171	G1-221	G3-251	G3-301	G3-351	G6-45x	G6-55x	G6-65x	G10-65x	G10-85x	G20-85x	G20-A0x	
Arm Length (mm) Horiz. (J1 + J2)		75 + 100 = 175	125 + 100 = 225	120 + 130 = 250	170 + 130 + 300	220 + 130 = 350	200 + 250 = 450	300 + 250 = 550	400 + 250 = 650	250 + 400 = 650	450 + 400 = 850	450 + 400 = 850	600 + 400 = 1000		
Payload (kg) Max. / Rated		Max. / Rated	1	/ 0.5	3 / 1		6/3		10	15	20 / 10				
Repeatability	lity J1 + J2 +/-0.005 +/-0.008 +/-0.008 +/-0.010		.010	+/-0.015 +/-0.010			+/-0.025 +/-0.010		+/-0.025 +/-0.010						
	mm J3 +/-0.010 +/-0.010														
	deg	J4	+/-0	.010	+/-0.005			+/-0.005			+/-0.005		+/-0.005		
Cycle Time			0.29*1	0.30*1	0.36*2	0.37*2	0.37*2	0.33*2	0.36*2	0.38*2	0.34*3	0.37*3	0.37*3 0.42*3		
Max. Operating	mm/sec	J1 + J2	2,630	3,000	3,550	3,950	4,350	6,440	7,170	7,900	8,800	11,000	11,000	11,500	
Speed	IIIII//360	J3 (Std / Ext)	1,2	200		1,100			1,100 / 2,350			/ 2,350	1,100 / 2,350		
	deg/sec	J4	30	000		3000			2400			100	1700		
Motor Wattage (W)			50 / 50 / 5	50 / 50		200 / 150 / 150 / 15	0	400 / 400 / 200 / 100			750 / 600	0 / 400 / 150	750 / 600 / 400 / 150		
Insertion Force			<u> </u>	5.1 kgf)		150N (15.3 kgf)			150N (15.3 kgf)			25.5 kgf)	250N (25.5 kgf)		
U inertia	kg₊m²	Max. / Rated		1 / 0.0003	3 0.05 / 0.005				0.12 / 0.01			0.25 / 0.02		0.45 / 0.05	
Axis Motion		Floor Mount	+/-	125		+/-140		+/-152		+/-152		+/-152			
Range	J1 (deg)	Ceiling Mount	-	-	-	+/-115	+/-120	+/-120	+/-^	52	+/-107	+/-152	+/-1		
	` "	Wall Mount	-	-	-	+/-115	+/-120	+/-105	+/-135	+/-148	+/-107	+/-107	+/-		
		Floor Mount	+/-140*5 +/-152*5		+/-141*5 +/-142*5		+/-141.5*4 +/-147.5*4		+/-152.5*4		+/-152.5*4				
	J2 (deg)	Ceiling Mount	-	-	-	+/-135	+/-142	+/-130	+/-14		+/-130	+/-152.5	+/-15		
		Wall Mount	-	-	-	+/-135	+/-142	+/-130	+/-14		+/-130	+/-152.5	+/-152.5		
J3 (mm)		All		(80)*6	150* ⁵ (120)* ⁶			180 (330)*5 / 150 (300)*6		180 (420)*5 / 150 (390)*6		, ,	/ 150 (390)*6		
	J4 (deg) All +/- 360 +/- 360					+/- 360			+/- 360		+/- 360				
User Lines		Electric		(15pin, 9pin)	15 lines (15pin)				24 lines (15pin, 9pin)	24 lines (15pin, 9pin)		24 lines (15pin, 9pin)		
		Air		, Ø6 x 2		Ø4 x 1, Ø6 x 2		Ø6 x 2, Ø4 x 2			Ø6 x 2, Ø4 x 2		Ø6 x 2, Ø4 x 2		
Z Axis Diameter (m	,			0 8	Ø16			Ø20			Ø25		Ø25		
Mounting Hole Foo	otprint (mm)		125 x 8	8 (4-M6)	120 x 120 (4-M8)			150 x 150 (4-M8)			0 (4-M12)		0 (4-M12)		
Weight (kg)		Floor Mount		8	14			7	28	46	48	48	50		
		Ceiling Mount	-	-	- 14			7	28	46	48	48	50		
		Wall Mount	-	-	- 14		29 29.5		29.5	51	53	53	55		
Environmental		Temperature						5 - 40 deg C							
O C C C C C C C C C C C C C C C C C C C	<u> </u>						10 - 80% (non condensing)								
Optional Arm								Tabletop, Ceiling, Wall							
Configurations		Clean & ESD		ISO 3 Clean & ESD											
Dahat Caldas (N.)	IP Rating						IP54, IP65								
Robot Cables (Met								d) / 5M (optional) / 1							
Available Controlle	ers		Micro PowerDrive RC180, PC Based Controller RC620+												

^{*1:} Cycle time based on 0.5kg payload *2: Cycle time based on 1kg payload *3: Cycle time based on 2kg payload *4: Maximum motion range varies based on Z position *5: Standard Z Axis configuration *6: Clean/IP Z Axis configuration





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